CANbus • SAE J1939

Ranges: 0-10 to 0-250 inches

Industrial Grade • High Cycle Applications

Specification Summary:

GENERAL

Full Stroke Ranges	0-10 to 0-250 inches
Electrical Interface	CANbus SAE J1939
Protocol	Proprietary B
Accuracy	\dots ± 0.25% to ± 0.10% full stroke
Repeatability	± 0.02% full stroke
Resolution	± 0.003% full stroke
Measuring Cable	stainless steel or thermoplastic
Enclosure Material	hard anodized aluminum
Sensor	. plastic-hybrid precision potentiometer
Potentiometer Cycle Life	see ordering information
Maximum Retraction Acceleration	
Weight	5 lbs. max.

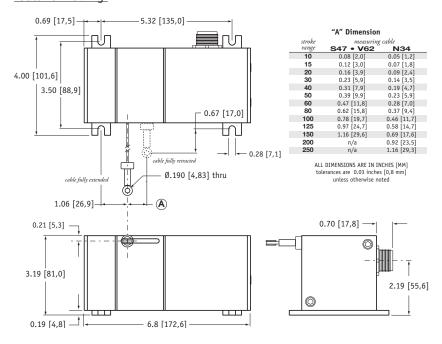
ELECTRICAL

Input Voltage	7 - 18 VDC
Input Current	60 mA max.
Baud Rate	125K, 250K, or 500K via DIP switches
Update Rate	10 ms. (20 ms. available—contact factory)

ENVIRONMENTAL

Environmental Suitability	NEMA 4/6, IP 65/67
Operating Temperature	40° to 185°F (-40° to 85°C)
Vibrationup t	to 10 G's to 2000 Hz maximum

Outline Drawing



PT5CN



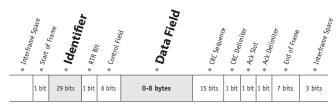
The PT5CN cable extension position transducer communicates linear position via the CANbus SAE J1939 interface providing a precision position feedback to your PLC. The PT5DN is offered in full stroke ranges up to 250 inches and a thermoplastic measuring cable for high cycle and rugged applications.

Because the PT5CN uses a potentiometer as it's sensing element, the position signal is "absolute" and does not have to be reset to a "home" position upon startup.

Output Signal



I/O Format and Settings



Identifier

ier –	Mess	age Pr	iority	Fut Us	ure se				939 R Propri							Da	ta Fie	eld Ty	pe*			Not	Used		N	lode 1	[D**		
Example –	1	0	0	0	0	1	1	1	1	1	1	1	1	0	1	0	1	0	0	1	1	0	0	1	1	1	1	1	1
Identifier Bit No. –	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Hex Value –			()			F	F			ı	F			į	5			3	3			3	3			ı	=	

*Sensor field data can be factory set to customer specific value. **Customer defined, set via Dips 1-6. Bit values shown for example only, see Address Setting below.

Data Field

 B_0 = LSB current % of measurement range byte

B₁ = MSB current % of measurement range byte

B₂ = LSB current measurement count byte

 $\mathbf{B_3} = \mathsf{MSB}$ current measurement count byte

$\mathbf{B}_{\mathbf{A}} = \text{error flaq}$	Velocit	y Data	Error	Flags		rement unt	Measu Rai		
B ₅ = error flag									
B ₆ = LSB velocity data byte B ₇ = MSB velocity data byte	B ₇	В ₆	B ₅	B ₄	В3	B ₂	B ₁	B ₀	

B ₇	В ₆	B ₅	B ₄	В3	В2	B ₁	B ₀	

Current Measurement Count

The Current Measurement Count (CMC) is the output data that indicates the present position of the measuring cable. The CMC is a 16-bit value that occupies bytes $\mathbf{B_2}$ and $\mathbf{B_3}$ of the data field. $\mathbf{B_2}$ is the LSB (least significant byte) and B3 is the MSB (most significant byte).

The CMC starts at 0x0000 with the measuring cable fully retracted and continues upward to the end of the stroke range stopping at OxFFFF. This holds true for all ranges.

Converting CMC to Linear Measurement

To convert the current measurment count to inches or millimeters, simply divide the count by 65,535 (total counts over the range) and then multiply that value by the full stroke range:

$$\left(\begin{array}{c} \frac{\text{current measurement}}{\text{count}} \\ \hline \\ 65,535 \end{array}\right) \chi \begin{array}{c} \text{full stroke} \\ \text{range} \end{array}$$

Sample Conversion:

If the full stroke range is 30 inches and the current position is OxOFF2 (4082 Decimal) then,

$$\left(\frac{4082}{65,535} \right) \chi 30.00 \text{ inches} = 1.87 \text{ inches}$$

If the full stroke range is 625 mm and the current position is OxOFF2 (4082 Decimal) then,

$$\left(\frac{4082}{65,535}\right)$$
 X 625 mm = 39 mm

B₇ B₆ B₅ B₄ B₃ B₂ B₁

Current % of Measurement Range

The Current % of Measurement Range is a 2-byte value that expresses the current linear position as a percentage of the entire full stroke range. Resolution is .1 % of the full stroke measurement range.

This value starts at 0x0000 at the beginning of the stroke and ends at 0x03E8.

Example:

Hex	Decimal	Percent
0000	0000	0.0%
0001	0001	0.1%
0002	0002	0.2%
03E8	1000	100.0%



Error Flags

0x55 (yellow LED on controller board) indicates that the sensor has begun to travel beyond the calibrated range of the internal position potentiometer.

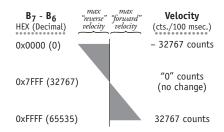
OxAA (red LED on controller board) indicates that the sensor has moved well beyond the calibrated range of the internal position potentiometer.

If either error flag occurs within the full stroke range of the sensor, the unit should be returned to the factory for repair and recalibration.

B₇ B₆ B₅ B₄ B₃ B₂ B₁ B₀

Velocity

Data in bytes $\mathbf{B_7}$ - $\mathbf{B_6}$ is the change in the \mathbf{CMC} (current measurement count) over a 100 msec time period. This data can then be used to calculate velocity in a post processing operation.



Velocity Calculation count change - 32767 full stroke range .1 sec. time period

Sample Calculations

Cable Extension (positive direction):

 $B_7 - B_6 = 0x89C6$ (43462 Dec), full stroke = 60 in.

$$\left(\frac{35270-32767}{.1 \text{ sec}}\right) X \left(\frac{60 \text{ in.}}{65,535}\right) = 22.92 \text{ in./ sec}$$

Cable Retraction (negative direction):

 $B_7 - B_6 = 0x61A8$ (25000 Dec), full stroke = 60 in.

$$\left(\frac{25000-32767}{.1 \text{ sec}}\right) \times \left(\frac{60 \text{ in.}}{65,535}\right) = -71.11 \text{ in./ sec.}$$

Setting the Address (Node ID) and Baud Rate

Address Setting (Node ID)

The Address Setting (Node ID) is set via 6 switches located on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

The DIP switch settings are binary starting with switch number $1 (= 2^0)$ and ending with switch number $6 (= 2^5)$.

The transmission baud rate may be either factory preset at the time of order or set manually at the time of installation.

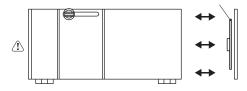
The baud rate can be set using switches 7 & 8 on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

CANBus Controller Board



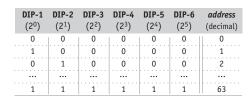
internal dip switches & controller board

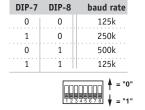
to gain access to the controller board, remove four Allen-Head Screws and remove end cover bracket.





Caution! Do Not Remove Spring-Side End Cover removing spring-side end cover could cause spring to become unseated and permanently damaged.





Ordering Information:

Model Number:



Sample Model Number:

PT5CN - 50 - S47 - FR - J - 500 - 32 - SC5

nange: measuring cable: A

Ğ measuring cable exit: interface:

0 baud rate: node ID:

electrical connection:

50 inches

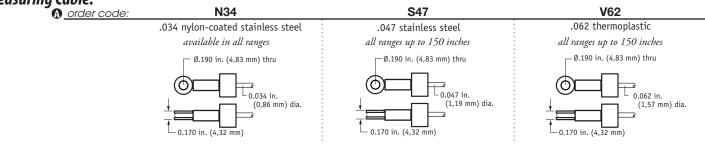
.047 stainless steel front CANbus SAE J1939 500 k bits/sec.

32 decimal 5-meter cordset with straight plug

Full Stroke Ranae:

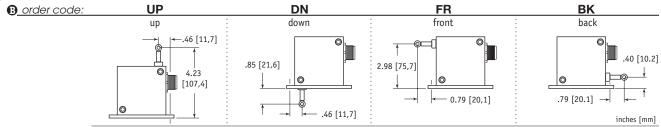
® <u>order code:</u>	10	15	20	25	30	40	50	60	80	100	125	150	200	250
full stroke range, min:	10 in.	15 in.	20 in.	25 in.	30 in.	40 in.	50 in.	60 in.	80 in.	100 in.	125 in.	150 in.	200 in.	250 in.
accuracy (±% of f.s.):	.75%	.6%	.5%	.5%	.5%	.3%	.3%	.25%	.25%	.25%	.25%	.18%	.18%	.18%
repeatability (±% of f.s.):	.1%	.1%	.05%	.05%	.05%	.05%	.05%	.02%	.02%	.02%	.02%	.02%	.02%	.02%
potentiometer cycle life:		2,50	0,000 cy	cles				500,00	500,000 cycles			250	,000 cyc	les
cable tension (20%):		41 ounces											21 o	unces
max. cable velocity/acceleration:	300 in./sec ● 5 G's											120 in./se	ec • 2 G's	

Measuring Cable:



Ordering Information (cont.)

Cable Exit:



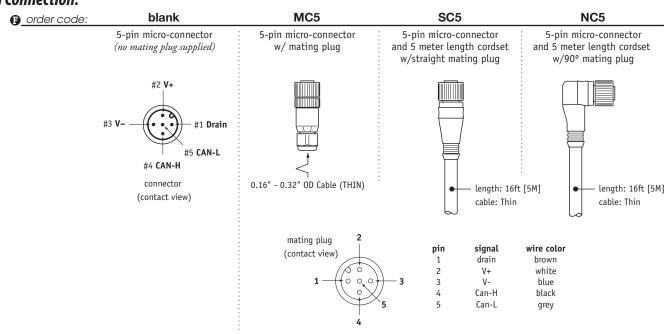
Baud Rate:

norder code:	125	250	500
	125 kbaud	250 kbaud	500 kbaud

Node ID:

B order code:	0	1	2	•••	62	63		
		sel	ect address	(0 - 63 Decim	nal)			

Electrical Connection:



version: 5.1 last updated: December 3, 2010

PT5CN | 84

