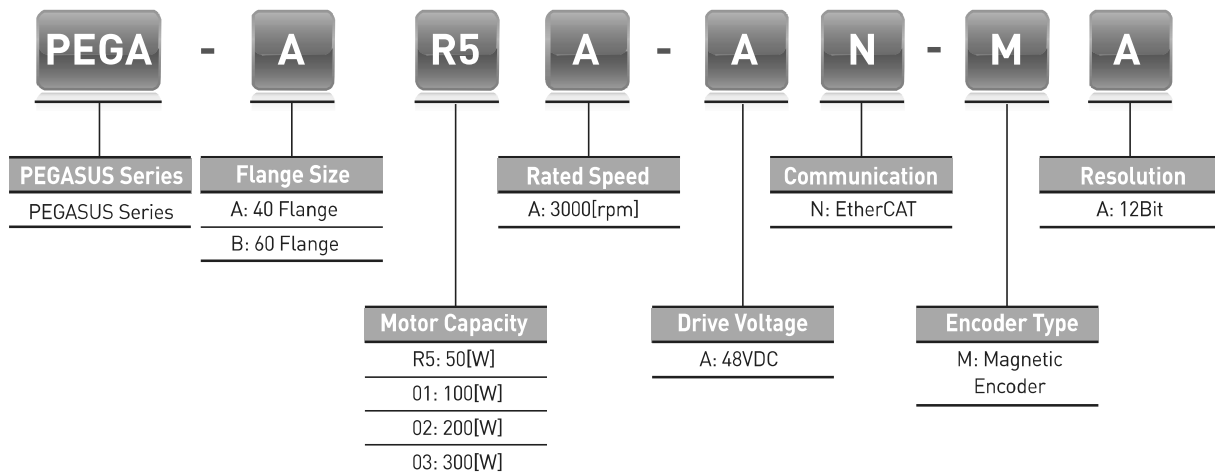


PEGA Series



Servo Drive Designation



Integrated Servo System Type **PEGA**

Enhanced efficiency integrated servo system

- Cost effective from installation by integrated system of motor, encoder cable and drive
- Maximization for useful space when installed at limited and small space
- High effectiveness for application of multi axis because there is no limitation for space of installation

Real-time control through EtherCAT

- High speed, Real-time capability and Synchronization mechanism
- Improved EtherCAT communication speed
- Supporting CoE, EoE and FoE



- 1** Input / Output Signal Connector (CN1)
 - This Connector is for Sequence Input / Output Signals
- 2** EtherCAT Communication Output Port (OUT)
- 3** Status LED
 - It Indicates the current state of EtherCAT Communication
- 4** Power Connector (CN3)
- 5** EtherCAT Communication Input Port (IN)
- 6** Safety Connector (CN2)
 - This Connector connects Safety Devices
- 7** USB Connector (CN5, Mini B type)
 - This Connector is to Communicate With a PC
- 8** Node Address Setting Switch
 - This Switch is to set the node address of the drive
 - You can set the node addresses from 0 to 15

Servo Drive

Rated Values of Servo Drive

Rated	□40 50W (AR5A)	□40 100W (A01A)	□60 100W (B01A)	□60 200W (B02A)	□60 300W (B03A)
Continuous output current [Arms]	1.77	2.38	3.62	5	6.8
Maximum output current [Arms]	3.54	3.75	7.24	10	13.6
Input voltage	DC 48V ~ DC 60V				

Basic Specifications

Category		Details	
Use conditions	Control method	PWM controlled sine wave current driving method	
	Operating temperature/storage temperature	0~+40[°C] / -20~ +60[°C]	
	Operating humidity/storage humidity	Below 80% RH / Below 90% RH (no freeze or condensation)	
	Vibration-/impact-resistance	TBD	
	Degree of protection/degree of pollution	TBD	
	Altitude	1000m or lower	
	Other	To be free from electrostatic noise, strong electrolysis, or radiation.	
Performance	Speed variation	Load variation	At 0 to 100% load: ± 3% [at rated speed]
		Voltage variation	Rated voltage ±10%: 0% [at rated speed]
		Temperature variation	25°C: ±0.1% or less [at rated speed]
Input/output signal	Input signal	Input voltage range: DC 12 V - DC 30 V The 4-channel input signal can be assigned to 12 functions: POT, NOT, HOME, STOP, PCON, GAIN2, PCL, NCL, PROBE1, PROBE2, EMG, and ARST.	
	Output signal	Rated voltage and current: DC 24 V ± 10%, 120 [mA] The 2-channel output signal can be assigned to 11 functions: BRAKE, ALARM, RDY, ZSPD, INPOS1, TLMT, VLMT, INSPD, WARN, TGON, and INPOS2.	
Analog Monitor		Number of channels: 1, Output voltage range: ± 4V, Angular resolution: 12 bits, Stabilization time: 15 us	
USB communication	Connecting device	PC or USB storage medium	
	Communication standard	Conform to the USB 2.0 Full Speed Standard.	
	Function	Firmware download, parameter setting, adjustment, auxiliary functions, and parameter copy function.	
Dynamic brake (three-phase short-circuit)		Activates when servo alarm, servo OFF, or Emergency stop (POT, NOT and EMG) is input.	
Protection functions		Overcurrent, overload, current limit, overheat, overvoltage, undervoltage, overspeed, encoder error, position follow error, ect.	
Auxiliary functions		Gain adjustment, alarm history, JOG drive, programmed JOG drive, etc.	
Safety functions	Input	STO1 and STO2	
	Compatible standard	TBD	

EtherCAT Communication Specification

Category		Details
Communication standard	FoE	Firmware download
	EoE	Parameter setting, adjustment, auxiliary functions, and parameter copy through UDP.
	CoE	IEC 61158 Type12, IEC 61800-7 CiA 402 drive profile
Physical layer		100BASE-TX(IEEE802.3)
Connector		RJ45 x 2
Distance		Within 100 m between nodes
DC (Distributed Clock)		Sync by DC mode
LED Display		• L/A0(Link/Act IN) • L/A1(Link/Act OUT) • RUN • ERR
Cia402 drive Profile		Supports CSP, CSV, CST, PP, PV, PT, and HM Modes.

Encoder Specification

Category	Details
Encoder Type	Magnetic Encoder (12bit)

Motor Specification

Model	Unit	□40 50W	□40 100W	□60 100W	□60 200W	□60 300W
Rated Torque	[Kgf cm]	1.62	3.25	3.25	6.50	9.74
Max. Torque	[Kgf cm]	3.24	4.88	6.50	13.0	19.48
Rated Speed	[rpm]	3000	2400	3000	3000	3000
Max Speed	[rpm]	3000	3000	3000	3000	3000
Inertia	[Kg m² x10-4]	0.0240	0.0450	0.114	0.182	0.321