## 6ES7516-3AN00-0AB0





\*\*\*Spare part\*\*\* SIMATIC S7-1500, CPU 1516-3 PN/DP, Central processing unit with Work memory 1 MB for program and 5 MB for data, 1st interface, PROFINET IRT with 2-port switch, 2nd interface, Ethernet, 3rd interface, PROFIBUS, 10 ns bit performance, SIMATIC Memory Card required

General information	
Product type designation	CPU 1516-3 PN/DP
HW functional status	FS05
Firmware version	V1.8
Product function	
<ul> <li>Isochronous mode</li> </ul>	Yes; With minimum OB 6x cycle of 375 µs
Engineering with	
<ul> <li>STEP 7 TIA Portal configurable/integrated from version</li> </ul>	V13 SP1 Update 4
Configuration control	
via dataset	Yes
Display	
Screen diagonal [cm]	6.1 cm
Control elements	
Number of keys	6
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
<ul> <li>Mains/voltage failure stored energy time</li> </ul>	5 ms
Input current	
Current consumption (rated value)	0.85 A
Inrush current, max.	2.4 A; Rated value
l²t	0.02 A <sup>2</sup> ·s
Power	
Infeed power to the backplane bus	12 W
Power consumption from the backplane bus (balanced)	6.7 W
Power loss	
Power loss, typ.	7 W
Memory	
SIMATIC memory card required	Yes
Work memory	
• integrated (for program)	1 Mbyte
• integrated (for data)	5 Mbyte
Load memory	
<ul> <li>Plug-in (SIMATIC Memory Card), max.</li> </ul>	32 Gbyte

Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	10 ns
for word operations, typ.	12 ns
for fixed point arithmetic, typ.	16 ns
for floating point arithmetic, typ.	64 ns
CPU-blocks	
Number of elements (total)	6 000; Blocks (OB, FB, FC, DB) and UDTs
DB	0 000, 2,00,10 (02,12,10,22) and 02.10
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	5 Mbyte; For non-optimized block accesses, the max. size of the DB is 64 KB
FB	
Number range	0 65 535
• Size, max.	512 kbyte
FC	
Number range	0 65 535
• Size, max.	512 kbyte
OB	
• Size, max.	512 kbyte
<ul> <li>Number of free cycle OBs</li> </ul>	100
<ul> <li>Number of time alarm OBs</li> </ul>	20
<ul> <li>Number of delay alarm OBs</li> </ul>	20
<ul> <li>Number of cyclic interrupt OBs</li> </ul>	20
<ul> <li>Number of process alarm OBs</li> </ul>	50
<ul> <li>Number of DPV1 alarm OBs</li> </ul>	3
<ul> <li>Number of isochronous mode OBs</li> </ul>	2
<ul> <li>Number of technology synchronous alarm OBs</li> </ul>	2
<ul> <li>Number of startup OBs</li> </ul>	100
<ul> <li>Number of asynchronous error OBs</li> </ul>	4
<ul> <li>Number of synchronous error OBs</li> </ul>	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	512 kbyte; In total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 472 KB
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte

Deta blacka	
Data blocks	Voc
Retentivity adjustable     Retentivity proced	Yes
Retentivity preset  Local data	No
	64 khyte; may 16 KP per black
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	8 192; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	014.4.
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	Olihoda
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	20
Number of subprocess images, max.	32
Hardware configuration	
Number of distributed IO systems	20
Number of DP masters	
• integrated	1
• Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	DO INSCITED IN TOTAL
• integrated	1
Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can
VIA CIVI	be inserted in total
Rack	
Modules per rack, max.	32; CPU + 31 modules
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
<ul><li>supported</li></ul>	Yes
• to DP, master	Yes
• in AS, master	Yes
• in AS, slave	Yes
on Ethernet via NTP	Yes
Interfaces	
Number of PROFINET interfaces	2
Number of PROFIBUS interfaces	1
1. Interface	
Interface types	
RJ 45 (Ethernet)	Yes; X1
Number of ports	2
integrated switch	Yes
Protocols	
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes
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Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— Isochronous mode	Yes
— IRT	Yes
— PROFlenergy	Yes
<ul> <li>Prioritized startup</li> </ul>	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	256; In total, up to 768 distributed I/O devices can be connected via PROFIBUS or PROFINET
<ul> <li>Of which IO devices with IRT, max.</li> </ul>	64
<ul> <li>Number of connectable IO Devices for RT, max.</li> </ul>	256
— of which in line, max.	256
<ul> <li>Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8
<ul> <li>Number of IO Devices per tool, max.</li> </ul>	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 250 μs	$250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 500 $\mu s$ of the isochronous OB is decisive
— for send cycle of 500 μs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
With IRT and parameterization of "odd" send cycles	Update time = set "odd" send clock (any multiple of 125 $\mu$ s: 375 $\mu$ s, 625 $\mu$ s 3 875 $\mu$ s)
Update time for RT	
— for send cycle of 250 μs	250 μs to 128 ms
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	V
— PG/OP communication	Yes
— Isochronous mode	No V
— IRT	Yes
— PROFlenergy	Yes
— Shared device	Yes
<ul> <li>Number of IO Controllers with shared device, max.</li> </ul>	4
2. Interface	
Interface types	
• RJ 45 (Ethernet)	Yes; X2
Number of ports	1
• integrated switch	No
Protocols	
PROFINET IO Controller	No
PROFINET IO Device	No
SIMATIC communication	Yes
Open IE communication	Yes
Web server	Yes
3. Interface	
Interface types	
• RS 485	Yes
Number of ports	1
Protocols	
PROFIBUS DP master	Yes
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PROFIBUS DP slave	No
SIMATIC communication	Yes
PROFIBUS DP master	166
Number of connections, max.	48; for the integrated PROFIBUS DP interface
Number of DP slaves, max.	125; In total, up to 768 distributed I/O devices can be connected via PROFIBUS or PROFINET
Services	
— PG/OP communication	Yes
— Equidistance	Yes
<ul> <li>Isochronous mode</li> </ul>	Yes
<ul> <li>Activation/deactivation of DP slaves</li> </ul>	Yes
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
Autonegotiation	Yes
Autocrossing	Yes
Industrial Ethernet status LED	Yes
RS 485	
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	No
Number of connections	
Number of connections, max.	256; via integrated interfaces of the CPU and connected CPs / CMs
Number of connections reserved for ES/HMI/web	10
<ul> <li>Number of connections via integrated interfaces</li> </ul>	128
<ul> <li>Number of S7 routing paths</li> </ul>	16
Redundancy mode	
Media redundancy	
— MRP	Yes; as MRP redundancy manager and/or MRP client; max. number of
	devices in the ring: 50
<ul> <li>Switchover time on line break, typ.</li> </ul>	200 ms
<ul> <li>Number of stations in the ring, max.</li> </ul>	50
SIMATIC communication	
S7 routing	Yes
<ul> <li>Data record routing</li> </ul>	Yes
<ul> <li>S7 communication, as server</li> </ul>	Yes
<ul> <li>S7 communication, as client</li> </ul>	Yes
<ul> <li>User data per job, max.</li> </ul>	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
<ul> <li>several passive connections per port, supported</li> </ul>	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	1 472 byte
• DHCP	No
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Web server	
• HTTP	Yes; Standard and user-defined pages
• HTTPS	Yes; Standard and user-defined pages
Further protocols	
MODBUS	Yes; MODBUS TCP
Isochronous mode	
Equidistance	Yes
S7 message functions	
Number of login stations for message functions, max.	32
	V-

	V
Program alarms	Yes
Number of configurable program messages, max.	10 000
Number of simultaneously active program alarms	
<ul> <li>Number of program alarms</li> </ul>	600
<ul> <li>Number of alarms for system diagnostics</li> </ul>	200
<ul> <li>Number of alarms for motion technology objects</li> </ul>	160
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 8 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Status/control	
Status/control variable	Yes
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
Number of variables, max.	γ,,,,,,, .
— of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	200, poi jou
Forcing, variables	Peripheral inputs/outputs
<ul><li>Number of variables, max.</li></ul>	200
	200
Diagnostic buffer	Voc
Present     Number of entries, may	Yes
Number of entries, max.	3 200
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
<ul> <li>Connection display LINK TX/RX</li> </ul>	Yes
Supported technology objects	
Motion Control	Yes
Speed-controlled axis	
— Number of speed-controlled axes, max.	30; Requirement: There must be no other motion technology objects
	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Positioning axis	created; note: The number of axes affects the cycle time of the PLC
<ul> <li>Number of positioning axes, max.</li> </ul>	created; note: The number of axes affects the cycle time of the PLC
	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC
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<ul><li>— Number of positioning axes, max.</li><li>• Synchronized axes (relative gear synchronization)</li></ul>	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC
<ul> <li>Number of positioning axes, max.</li> <li>Synchronized axes (relative gear synchronization)</li> <li>Number of axes, max.</li> </ul>	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC
<ul> <li>Number of positioning axes, max.</li> <li>Synchronized axes (relative gear synchronization)</li> <li>Number of axes, max.</li> <li>External encoders</li> </ul>	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC
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Number of positioning axes, max.  Synchronized axes (relative gear synchronization)  Number of axes, max.  External encoders  Number of external encoders, max.  Controller	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
- Number of positioning axes, max.  Synchronized axes (relative gear synchronization) - Number of axes, max.  External encoders - Number of external encoders, max.  Controller PID_Compact	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  Yes; Universal PID controller with integrated optimization
<ul> <li>Number of positioning axes, max.</li> <li>Synchronized axes (relative gear synchronization)         <ul> <li>Number of axes, max.</li> </ul> </li> <li>External encoders         <ul> <li>Number of external encoders, max.</li> </ul> </li> <li>Controller         <ul> <li>PID_Compact</li> <li>PID_3Step</li> </ul> </li> </ul>	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
<ul> <li>Number of positioning axes, max.</li> <li>Synchronized axes (relative gear synchronization)         <ul> <li>Number of axes, max.</li> </ul> </li> <li>External encoders         <ul> <li>Number of external encoders, max.</li> </ul> </li> <li>Controller         <ul> <li>PID_Compact</li> <li>PID_3Step</li> <li>PID-Temp</li> </ul> </li> </ul>	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
- Number of positioning axes, max.  Synchronized axes (relative gear synchronization) - Number of axes, max.  External encoders - Number of external encoders, max.  Controller PID_Compact PID_3Step PID-Temp Counting and measuring	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for temperature
- Number of positioning axes, max.  Synchronized axes (relative gear synchronization) - Number of axes, max.  External encoders - Number of external encoders, max.  Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter  Ambient conditions	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for temperature
- Number of positioning axes, max.  Synchronized axes (relative gear synchronization) - Number of axes, max.  External encoders - Number of external encoders, max.  Controller PID_Compact PID_3Step PID-Temp  Counting and measuring High-speed counter  Ambient conditions  Ambient temperature during operation	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
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- Number of positioning axes, max.  Synchronized axes (relative gear synchronization) - Number of axes, max.  External encoders - Number of external encoders, max.  Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter  Ambient conditions  Ambient temperature during operation horizontal installation, min.	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  0 °C 60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the
- Number of positioning axes, max.  Synchronized axes (relative gear synchronization) - Number of axes, max.  External encoders - Number of external encoders, max.  Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter  Ambient conditions  Ambient temperature during operation horizontal installation, min. horizontal installation, max.	created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  15; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  30; Requirement: There must be no other motion technology objects created; note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  0 °C 60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off

	display is switched off
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— GRAPH	Yes
Know-how protection	
<ul> <li>User program protection/password protection</li> </ul>	Yes
<ul> <li>Copy protection</li> </ul>	Yes
Block protection	Yes
Access protection	
<ul> <li>Password for display</li> </ul>	Yes
<ul> <li>Protection level: Write protection</li> </ul>	Yes
<ul> <li>Protection level: Read/write protection</li> </ul>	Yes
Protection level: Complete protection	Yes
programming / cycle time monitoring / header	
<ul> <li>lower limit</li> </ul>	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	70 mm
Height	147 mm
Depth	129 mm
Weights	
Weight, approx.	845 g
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